

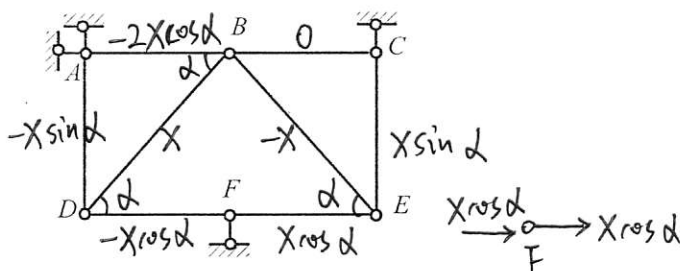
(请在答题纸上作答, 试卷上做答无效, 试后本卷必须与答题纸一同交回)

科目名称: 结构力学

适用专业: 工程力学, 岩土工程, 结构工程, 防灾减灾工程及防护工程, 桥梁与隧道工程

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1、计算图示体系的自由度, 试分析其体系的几何组成。(20分)



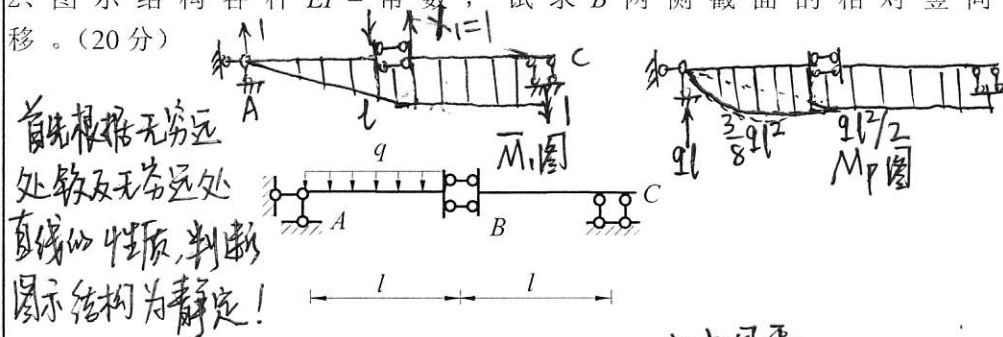
计算自由度: $W = 6 \times 2 - 8 - 4 = 0$

采用零载法, BD 杆内力设为 X

F 结点平衡: $\sum F_{Fx} = 0 \quad X \cos \alpha + X \cos \alpha = 0 \quad X = 0$

由此可知: 图示体系各杆内力均为 0, 即无自内力存在, 故体系自由度为 0, 为无多余约束几何不变体系。


2、图示结构各杆 $EI =$ 常数, 试求 B 两侧截面的相对竖向位移。(20分)



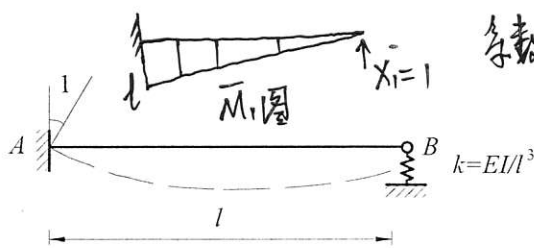
首先根据无穷远处弯矩及无穷远处直线的性质, 判断图示结构为静定!

分块图乘

$$\Delta_{yB} = \sum \int \frac{\bar{M}_i M_p}{EI} dx = \frac{1}{EI} \left(\frac{2}{3} \times l \times \frac{1}{8} ql^2 \times \frac{l}{2} + \frac{1}{2} \times \frac{ql^2}{2} \times l \times \frac{2}{3} l \right) + (l \times l \times \frac{1}{2} ql^2) \times \frac{1}{EI} = \frac{17ql^4}{24EI}$$

方法2.  象数和自由项: $\delta_{11} = \frac{1}{EI} (\frac{1}{2} \times l \times l \times \frac{2}{3}) = \frac{l^3}{3EI}$
 $\delta_{1k} = \frac{1}{EI} \times \frac{1}{l} = \frac{1}{EI}$
 加法基本方程 $(\delta_{11} + \delta_{1k}) \cdot X_1 = 1$ 代入解得 $X_1 = \frac{3EI}{4l}$
 由 $M = X_1 \cdot \bar{M}_1$ 可得 M图。
 或者: $\delta_{11} = \frac{4l}{3EI}$
 两步并作一步

3、用力法求图示梁的M图。 $EI =$ 常数,已知B支座的弹簧刚度为k。(20分)



象数和自由项: $\delta_{11} = \frac{1}{2EI} \times l \times l \times \frac{2}{3} l = \frac{l^3}{3EI}$
 $\Delta_{10} = -1 \times l = -l$

力法基本方程: $\delta_{11} \cdot X_1 + \Delta_{10} = -\frac{X_1}{k}$ 代入后解得 $X_1 = \frac{3EI}{4l^2}$

由 $M = X_1 \cdot \bar{M}_1$ 可得 M图。

4、用位移法计算图示刚架,作M图。(15分)

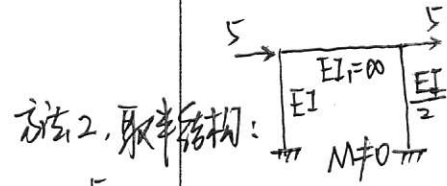
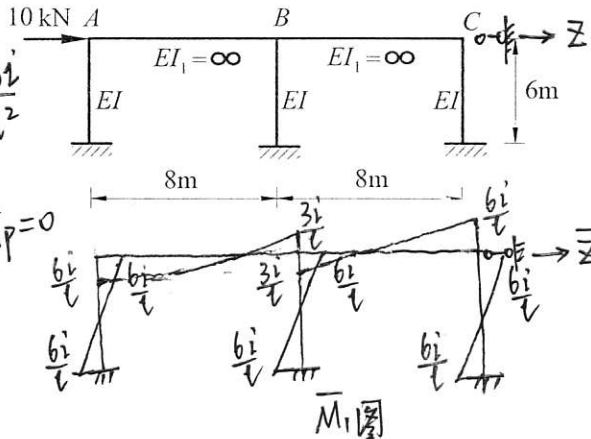
象数和自由项:

$Y_{11} = 3 \times \frac{12i}{l^2} = \frac{36i}{l^2}$
 $Y_{1P} = -10kN$

基本方程: $Y_{11} \cdot Z_1 + Y_{1P} = 0$

代入解得 $Z_1 = \frac{+5l^2}{18i}$

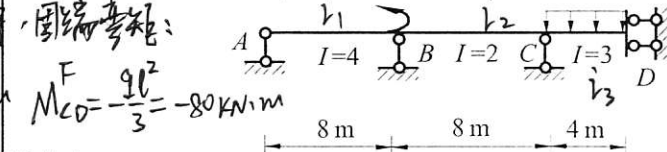
$M = Z_1 \cdot \bar{M}_1 + \frac{M_{1P}}{=0}$



同样可解得
 横梁水平向侧移
 为 $\frac{5l^2}{18i}$

5、用力矩分配法绘制图示梁的弯矩图。 EI 为常数。(计算二轮)(20分)

$i_1 = \frac{EI_1}{l_1} = \frac{4E}{8} = \frac{E}{2}$ $i_2 = \frac{2E}{8} = \frac{E}{4}$ $i_3 = \frac{3E}{4}$



集中力偶记入AB杆

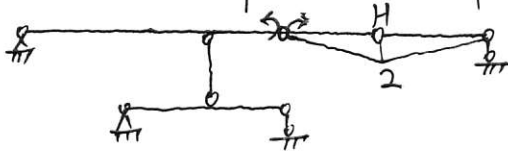
$M_{BA}^F = -20kN \cdot m$

$M_{CD}^F = -\frac{9l^2}{3} = -80kN \cdot m$

$M_{DC}^F = -\frac{9l^2}{6} = -40kN \cdot m$

杆端:	AB	BA	BC	CB	CD	DC
μ	/	0.6	0.4	$\frac{4}{7}$	$\frac{3}{7}$	/
M^F	0	-20	0	0	-80	-40
			22.84	45.68	34.32	-34.32
		-1.704	-1.36	2.568		
			0.162	0.324	0.244	-0.244
			-0.097	-0.065	0.053	
			0.01	-0.019	0.014	-0.014
M	0	-21.801	21.811	45.422	-45.422	-74.578

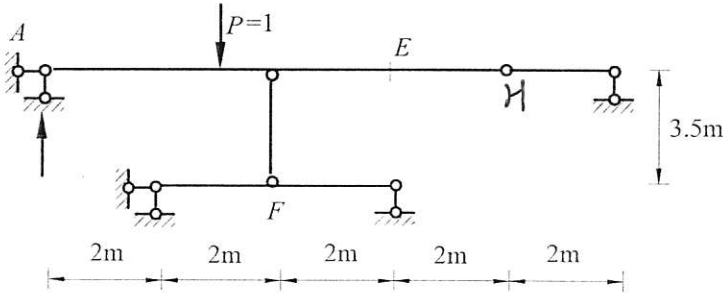
② M_E 影响线: 虚功方程: $\bar{M}_E \cdot \delta \theta_E + 1 \times \delta p = 0$ $\bar{M}_E = -\frac{\delta p}{\delta \theta_E}$ 由此定出 M_E 影响线大致形状. 现只须求 y_H 即可. 令 $P=1$ 作用于 H , 可求得 $y_H=2$



M_E 影响线.

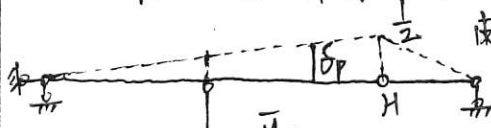
总结: 作影响线用联合法, (有时直接简化为机动法) 比较方便!!!

6、作图示结构的 M_E 、 M_F 影响线。(20分)



采用联合法作影响线:

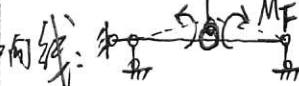
① M_F 影响线: 下层梁结于 F 处变为铰接, 虚功方程: $\bar{M}_F \cdot \delta \theta_F + 1 \times \delta p = 0$ $M_F = -\frac{\delta p}{\delta \theta_F}$



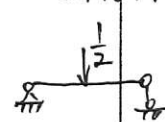
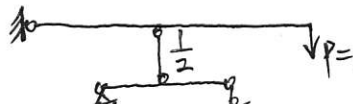
由此确定出 M_F 影响线大致形状. 现只须求 y_H 即可.

令 $P=1$ 作用于 H 点, H 点左边为基本结构. 右边为附属.

M_F 影响线:



图①



$$y_H = \frac{1 \times 4}{4} = \frac{1}{2}$$

7、求图示体系的自振频率。设 $EI = \text{常数}$ 。(15分)

先判断结构为超静定, 采用刚度法.

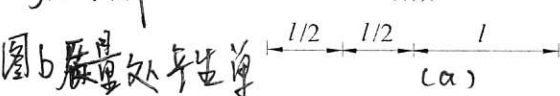
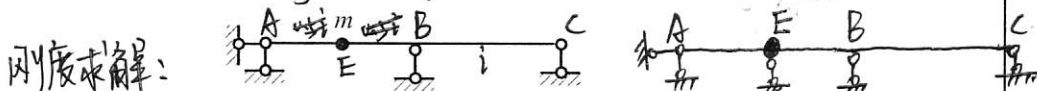
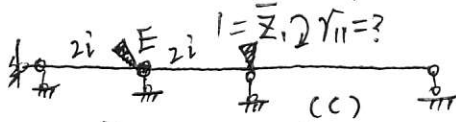


图 b 质量处产生单位位移所需施加的力即为刚度 k 。采用位移法可解出 k 值.



$$\gamma_{11} = 8i + 3i = 11i \quad i = \frac{EI}{L}$$

$$\gamma_{12} = \gamma_{21} = 4i$$

$$\gamma_{22} = 3 \times 2i + 8i = 14i$$

$$\gamma_{1\Delta} = \frac{6 \times 2i}{\frac{1}{2}} = \frac{24i}{\frac{1}{2}}$$

$$\gamma_{2\Delta} = \frac{24i}{\frac{1}{2}} - \frac{3 \times 2i}{\frac{1}{2}} = \frac{12i}{\frac{1}{2}}$$

力法典型方程: $\gamma_{11} z_1 + \gamma_{12} z_2 + \gamma_{1\Delta} = 0$
 $\gamma_{21} z_1 + \gamma_{22} z_2 + \gamma_{2\Delta} = 0$

代入解得 $z_1 = \frac{-48}{23i}$ $z_2 = -\frac{6}{23i}$

由此可求得 $M_{EA} = \frac{-312}{23i}$ $M_{EB} = \frac{312}{23i}$ $M_{BE} = \frac{144i}{23i}$

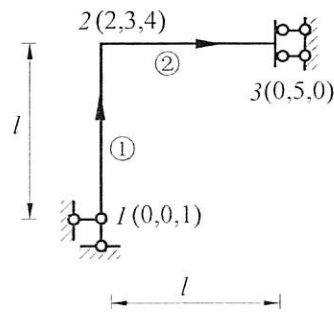
$$k = \frac{-M_{EA}}{\frac{1}{2}} + \frac{M_{EB} + M_{BE}}{\frac{1}{2}} = \frac{1536i}{23i^2}$$

振动方程: $-m\ddot{y} - ky = 0 \quad \ddot{y} + \frac{k}{m}y = 0$

$$\omega = \sqrt{\frac{k}{m}} = 8.17 \sqrt{\frac{i}{m l^2}} = 8.17 \sqrt{\frac{EI}{m l^3}}$$

8、用先处理法写出图示刚架结构刚度矩阵的元素

$K_{22}, K_{34}, K_{15}, K_{45}$ 。EI, EA 均为常数。(20分)



$$T = \begin{pmatrix} \cos\alpha & \sin\alpha & 0 & 0 & 0 & 0 \\ -\sin\alpha & \cos\alpha & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & \cos\alpha & \sin\alpha & 0 \\ 0 & 0 & 0 & -\sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

定位向量 $\lambda^{\text{①}} = (0, 0, 1, 2, 3, 4)^T$ $\lambda^{\text{②}} = (2, 3, 4, 0, 5, 0)^T$

$K^{\text{①}} =$ 交叉处为数字 即单元刚度矩阵给出

$$K^{\text{①}} = T^T K^{\text{①}} T = \begin{pmatrix} 0 & 0 & 1 & 2 & 3 & 4 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & EA & 0 & 0 & 0 & 0 \\ 0 & 0 & 4EI/l & 6EI/l & 0 & 0 \\ 0 & 0 & 6EI/l & 12EI/l & 0 & 0 \\ 0 & 0 & 0 & 0 & EA & 0 \\ 0 & 0 & 0 & 0 & 0 & EA \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

其中 $T = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$

$$K_{22} = \frac{12EI}{l^3} + \frac{EA}{l} \quad K_{34} = \frac{6EI}{l^2}$$

$$K_{15} = 0 \quad K_{45} = -\frac{6EI}{l^2}$$

$$K^{\text{①}} = \bar{K}^{\text{①}} =$$

附:

2	3	4	0	5	0
$\frac{EA}{l}$	0	0	$-\frac{EA}{l}$	0	0
0	$\frac{12EI}{l^3}$	$\frac{6EI}{l^2}$	0	$-\frac{12EI}{l^3}$	$\frac{6EI}{l^2}$
0	$\frac{6EI}{l^2}$	$\frac{4EI}{l}$	0	$-\frac{6EI}{l^2}$	$\frac{2EI}{l}$
$-\frac{EA}{l}$	0	0	$\frac{EA}{l}$	0	0
0	$-\frac{12EI}{l^3}$	$-\frac{6EI}{l^2}$	0	$\frac{12EI}{l^3}$	$-\frac{6EI}{l^2}$
0	$-\frac{6EI}{l^2}$	$-\frac{2EI}{l}$	0	$\frac{6EI}{l^2}$	$\frac{4EI}{l}$

法
先处理
总体刚度矩阵:

$$K = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 1 & \frac{4EI}{l} & \frac{6EI}{l^2} & 0 & \frac{2EI}{l} & 0 \\ 2 & \frac{6EI}{l^2} & \frac{12EI}{l^3} + \frac{EA}{l} & 0 & \frac{6EI}{l^2} & 0 \\ 3 & 0 & 0 & \frac{EA}{l} + \frac{12EI}{l^3} & \frac{6EI}{l^2} & -\frac{12EI}{l^3} \\ 4 & \frac{2EI}{l} & \frac{6EI}{l^2} & \frac{6EI}{l^2} & \frac{8EI}{l} & -\frac{6EI}{l^2} \\ 5 & 0 & 0 & -\frac{12EI}{l^3} & -\frac{6EI}{l^2} & \frac{12EI}{l^3} \end{pmatrix}$$