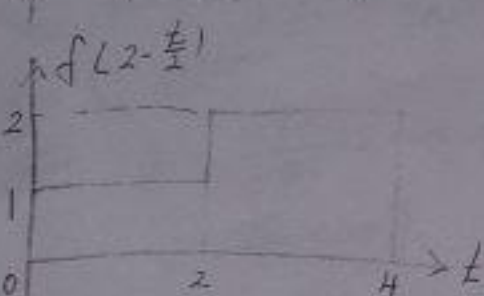
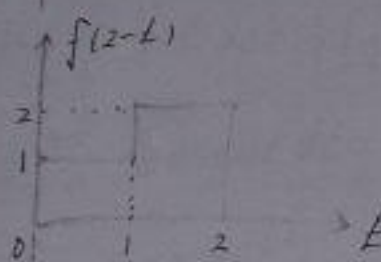
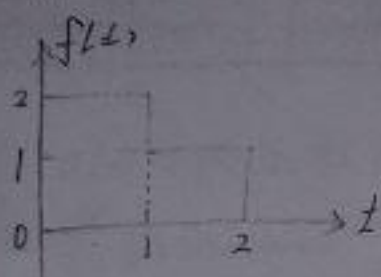


2001



$$f(t) \leftrightarrow F(j\omega) \quad f(-t) \xleftrightarrow{F} F(-j\omega)$$

$$\therefore F_1(j\omega) = e^{-j2\omega} F(-j\omega)$$

$$F_1(j\omega) = e^{-j2\omega} F(-j\omega)$$

$$f(t) \leftrightarrow F(j\omega) \quad f(4-t) \leftrightarrow e^{-j4\omega} F(-j\omega)$$

$$\therefore F_2(j\omega) = \frac{1}{2} e^{-j\frac{4\omega}{2}} F(-j2\omega) = 2e^{-j8\omega} F(-j2\omega)$$

$$2. \text{ 由题知: } g(t) \leftrightarrow G(j\omega)$$

$$g\left(\frac{t+b}{a}\right) \leftrightarrow \frac{1}{|a|} e^{-j\frac{b\omega}{a}} G\left(\frac{j\omega}{a}\right) = |a| e^{-j\frac{b\omega}{a}} G\left(\frac{j\omega}{a}\right)$$

卷积定理

$$\therefore R(j\omega) = F(j\omega) \cdot |a| e^{-j\frac{b\omega}{a}} G\left(\frac{j\omega}{a}\right) = |a| e^{-j\frac{b\omega}{a}} F(j\omega) G\left(\frac{j\omega}{a}\right)$$

$$3. r(t) = \int_{-\infty}^{t+a} f(\tau) d\tau - \int_0^t f(\tau) d\tau = f(t) * h(t+a) - f(t) * h(t)$$

$$R(s) = F(s) \cdot \frac{e^{sa}}{s} - F(s) \cdot \frac{1}{s}$$

$$= -\frac{F(s)}{s} (e^{sa} - 1)$$

4

$$Y(z) = X(0) + [X(0) + X(1)]z^{-1} + [X(0) + X(1) + X(2)]z^{-2} + [X(0) + X(1) + X(2) + X(3)]z^{-3} + \dots$$

$$z^{-1}Y(z) = X(0)z^{-1} + [X(0) + X(1)]z^{-2} + [X(0) + X(1) + X(2)]z^{-3} + \dots$$

$$Y(z)(1 - z^{-1}) = X(0) + X(1)z^{-1} + X(2)z^{-2} + \dots = X(z)$$

$$Y(z) = \frac{X(z)}{1 - z^{-1}}$$

二. 由题知:

$$r(t) = [e^{t/2} * h_1(t) * e^{t/2} * h_2(t)] * h_3(t)$$

$$* [h_1(t) - h_2(t)] * h_3(t)$$

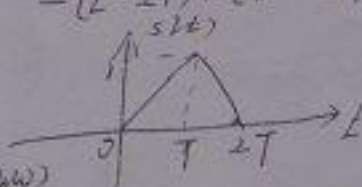
$$= e^{t/2} [h_1(t) * h_2(t)] * h_3(t)$$

$$* [h_1(t) - h_2(t)] * h_3(t)$$

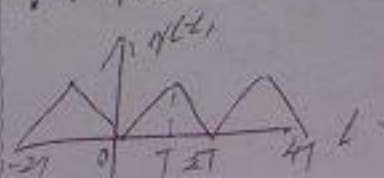
$$= e^{t/2} * [t * n(t-2) * n(t-2) + R(t-2T) * n(t-2T)]$$

$$\text{设 } S(t) = t * n(t-2) * n(t-2) + R(t-2T) * n(t-2T)$$

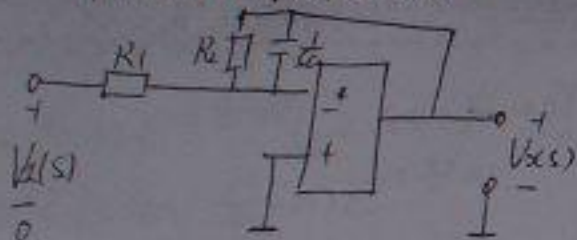
$$= t * n(t) - (t-T) * n(t-T) - [(t-T) * n(t-T) - (t-2T) * n(t-2T)] \quad \text{波形如下}$$



$$\therefore r(t) = e^{t/2} * S(t) = \sum_{n=0}^{\infty} S(t-2nT) e^{(t-2nT)/2}$$



7. 取样期间等效电路为

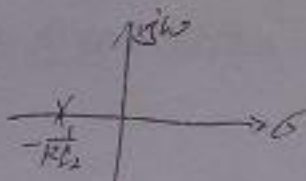


$$\frac{V_d(s) - 0}{R_1} = \frac{0 - V_x(s)}{R_2 + \frac{1}{sC}}$$

$$\frac{V_x(s)}{V_d(s)} = - \frac{\frac{R_2}{sC}}{R_1} = - \frac{R_2}{sC R_1}$$

$$H(s) = - \frac{1}{s + \frac{1}{CR_2}}$$

2. 极点 $s = -\frac{1}{CR_2}$



3. $f_{hL}(t) = -\frac{1}{R_1 C} e^{-\frac{1}{R_1 C} t} u(t)$

$R_2 C$ 为时间常数 $R_2 C$ 越小, $f_{hL}(t)$ 衰减的越快 C 越小, $f_{hL}(t)$ 初值越大

8.

1. 问题:

$$R(s) = [E(s) + K R(s)] \cdot \frac{s}{s^2 + 2s + 1}$$

$$R(s) \frac{s^2 + 2s + 1 - Ks}{s^2 + 2s + 1} = \frac{s}{s^2 + 2s + 1} E(s)$$

$$H(s) = \frac{R(s)}{E(s)} = \frac{s}{s^2 + (2-K)s + 1}$$

2. 系统要求稳定, 则极点应在左半平面

$$2-K > 0 \quad K < 2$$

9. 临界稳定时

$$H(s) = \frac{s}{s^2 + 1}$$

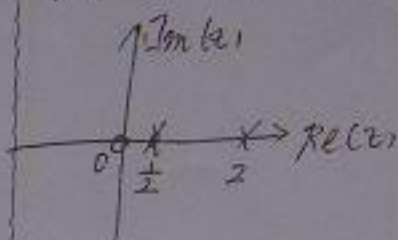
$$h_L(t) = \cos t u(t)$$

11.

$$X(z) = \frac{-3z}{z^2 - 5z + 2} = \frac{-3z}{(z-2)(z-1)}$$

零点 $z=0$

极点 $z_1=2 \quad z_2=\frac{1}{2}$



$$2. \frac{X(z)}{z} = \frac{-3}{(z-2)(z-1)} = \frac{-1}{z-2} + \frac{2}{z-1}$$

$$X(z) = \frac{-z}{z-2} + \frac{2z}{z-1}$$

① $|z| > 2$ 时

$$x(n) = [2^n + \frac{1}{2}^n] u(n)$$

② $|z| < 0.5$ 时

$$x(n) = -[\frac{1}{2}^n + 2^n] u(-n-1)$$

③ $0.5 < |z| < 2$ 时

$$x(n) = -(\frac{1}{2})^n u(n) + (2)^n u(-n-1)$$

九. 证明:

$$H(z) = \sum_{n=-\infty}^{\infty} h(n) z^{-n}$$

$$H(e^{j\omega}) = \sum_{n=-\infty}^{\infty} h(n) e^{j\omega n}$$

$$= h(n) e^{-j\omega n} + h(N-1-n) e^{j\omega(N-1-n)}$$

$$= h(n) e^{-j\frac{N-1}{2}\omega} (e^{j(\frac{N-1}{2}\omega - n)} + e^{-j(\frac{N-1}{2}\omega - n)})$$

~~$$= h(n) e^{-j\frac{N-1}{2}\omega} (e^{j(\frac{N-1}{2}\omega - n)} + e^{-j(\frac{N-1}{2}\omega - n)})$$~~

$$= h(n) e^{-j\frac{N-1}{2}\omega} [2 \cos(\frac{N-1}{2}\omega - n)]$$

$$= 2h(n) \cos(\frac{N-1}{2}\omega - n) e^{-j\frac{N-1}{2}\omega}$$

\therefore 对于 $H(e^{j\omega})$ 来说 $\varphi(\omega) = -\frac{N-1}{2}\omega$ ，该系统

具有线性相位。

+

解：

~~该系统为~~

~~$$x(t) = A e^{At} + B e^{Bt}$$~~

~~$$X(s) = A s + B e(s)$$~~

1. 零输入条件。设状态转移矩阵 $\Phi(t) =$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} e^{(sI - A)t}$$

$$\text{例: } \begin{bmatrix} 2e^{-2t} - e^{-3t} \\ e^{-2t} - e^{-3t} \end{bmatrix} = \Phi(t) \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -2e^{-2t} + 2e^{-3t} \\ -e^{-2t} + 2e^{-3t} \end{bmatrix} = \Phi(t) \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\therefore \begin{bmatrix} 2e^{-2t} - e^{-3t} & -2e^{-2t} + 2e^{-3t} \\ e^{-2t} - e^{-3t} & -e^{-2t} + 2e^{-3t} \end{bmatrix} = \Phi(t) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

~~$$= \Phi(t)$$~~

$$\Phi(t) = \begin{bmatrix} 2e^{-2t} - e^{-3t} & -2e^{-2t} + 2e^{-3t} \\ e^{-2t} - e^{-3t} & -e^{-2t} + 2e^{-3t} \end{bmatrix}$$

$$L[\Phi(t)] = \begin{bmatrix} \frac{2}{s+2} - \frac{1}{s+3} & -\frac{2}{s+2} + \frac{2}{s+3} \\ \frac{1}{s+2} - \frac{1}{s+3} & -\frac{1}{s+2} + \frac{2}{s+3} \end{bmatrix} = (sI - A)^{-1}$$

2. 由 1 知

$$(sI - A)^{-1} = \frac{1}{(s+2)(s+3)} \begin{bmatrix} 2s+6-s-2 & -2s-6+2s+4 \\ s+3-s-2 & -s-3+2s+4 \end{bmatrix}$$

$$= \frac{1}{(s+2)(s+3)} \begin{bmatrix} s+4 & -2 \\ 1 & s+1 \end{bmatrix}$$

$$= \frac{\begin{bmatrix} s+4 & -2 \\ 1 & s+1 \end{bmatrix}}{(s+2)(s+3)}$$

$$sI - A = \begin{bmatrix} s+1 & 2 \\ -1 & s+4 \end{bmatrix}$$

$$\therefore A = \begin{bmatrix} -1 & 2 \\ -1 & -4 \end{bmatrix}$$